

# **ME 321: FLUID MECHANICS-I**

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**Fluid dynamics** 

- Linear Momentum Equation
- Bernoulli Equation

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#### Recap



Reynolds transport theorem (RTT) for a fixed, nondeforming control volume (CV)

$$\left|\frac{d}{dt}\left(B_{\text{syst}}\right) = \frac{d}{dt}\left(\int_{CV}\beta\,\rho d\mathcal{H}\right) + \int_{CS}\beta\,\rho\left(\vec{\mathbf{V}}\cdot\hat{\mathbf{n}}\right)dA$$

This relation permits to change from a system approach to control volume approach.

where

 $B_{\text{syst}} = \text{any property of fluid (mass, momentum, enthalpy, etc.)}$ 

 $\beta$  = intensive property of fluid (per unit mass basis)

 $\rho$  = density of fluid

 $d\mathcal{V} = \text{elemental volume}$ 

 $(\vec{\mathbf{V}} \cdot \hat{\mathbf{n}}) dA$  = elemental volume flux

 $_{\rm V}$  = volume integral over the control volume (CV)

= surface integral over the control surface (CS)

Similar expression adopted by other books:

$$\frac{D}{Dt} (B_{\text{syst}}) = \frac{\partial}{\partial t} (\int_{CV} \beta \rho d\Psi) + \int_{CS} \beta \rho (\vec{\mathbf{V}} \cdot \hat{\mathbf{n}}) dA$$



## **Conservation of linear momentum**

ß



$$B = m \vec{\mathbf{V}} (\text{momentum}) ,$$

$$=\frac{m\mathbf{V}(\text{momentum})}{m \text{ (mass)}}=\vec{\mathbf{V}}$$

**RTT** takes the form of

$$\frac{d\left(m\vec{\mathbf{V}}\right)_{\rm sys}}{dt} = \frac{d}{dt} \int_{\rm CV} \vec{\mathbf{V}}\rho \,d\mathcal{V} + \int_{\rm CS} \vec{\mathbf{V}}\rho \left(\vec{\mathbf{V}}\cdot\hat{\mathbf{n}}\right) dA$$

$$\vec{\mathbf{V}} = u\hat{i} + v\hat{j} + w\hat{k} = (u, v, w)$$

#### Newton's second law of motion for a system is

Time rate of change of the linear momentum of the system

Sum of external forces acting on the system

$$\frac{d(m\vec{\mathbf{V}})_{\text{sys}}}{dt} = \sum \vec{F}_{\text{sys}} = \sum \vec{F}_{\text{contents of the control volume}}$$

Since when a control volume coincident with a system at an instant of time, the forces acting on the system and the forces acting on the contents of the coincident control volume are instantaneously identical.

# **Conservation of linear momentum**



For a control volume (CV) which is fixed and nondeforming, the Newton's second law of motion takes the following form:

$$\sum \vec{F}_{\text{contents of the control volume}} = \frac{d}{dt} \int_{CV} \vec{V} \rho \, d\mathcal{V} + \int_{CS} \vec{V} \rho \left(\vec{V} \cdot \hat{\mathbf{n}}\right) dA$$
  
Force contents of the control volume (CV) = Time rate of change of the linear momentum + Net rate of linear momentum through

of the contents of the

control volume (CV)

In fluid mechanics, there are two types of forces are to be considered,

(i) surface force,  $F_{\rm S}$  which acts on the surfaces on the CV (pressure and shear stress)

(ii) body force,  $F_{\rm B}$  which acts on the mass content of the CV (weight, electromagnetic force, etc.)

Then,

$$\sum \left( \vec{F}_{S} + \vec{F}_{B} \right) = \frac{d}{dt} \int_{CV} \vec{V} \rho \, d\mathcal{V} + \int_{CS} \vec{V} \rho \left( \vec{V} \cdot \hat{\mathbf{n}} \right) dA$$
\*\* Vector equations

quation

This is known as **momentum equation** Or equation of motion in Fluid dynamics



the control surface

(CS)

# **Conservation of linear momentum**



The momentum equation is a vector equation. Considering 3 components in Cartesian coordinate system (x, y, z), the momentum equation comes as:

$$x - \text{direction} : \sum \left( F_{S_x} + F_{B_x} \right) = \frac{d}{dt} \int_{CV} u\rho \, d\mathcal{V} + \int_{CS} u\rho \left( \vec{\mathbf{V}} \cdot \hat{\mathbf{n}} \right) dA$$

$$y - \text{direction} : \sum \left( F_{S_y} + F_{B_y} \right) = \frac{d}{dt} \int_{CV} v\rho \, d\mathcal{V} + \int_{CS} v\rho \left( \vec{\mathbf{V}} \cdot \hat{\mathbf{n}} \right) dA$$

$$z - \text{direction} : \sum \left( F_{S_z} + F_{B_z} \right) = \frac{d}{dt} \int_{CV} w\rho \, d\mathcal{V} + \int_{CS} w\rho \left( \vec{\mathbf{V}} \cdot \hat{\mathbf{n}} \right) dA$$

Applications of linear momentum equations will be discussed in later classes.

$$\vec{\mathbf{V}} = u\hat{i} + v\hat{j} + w\hat{k} = (u, v, w)$$



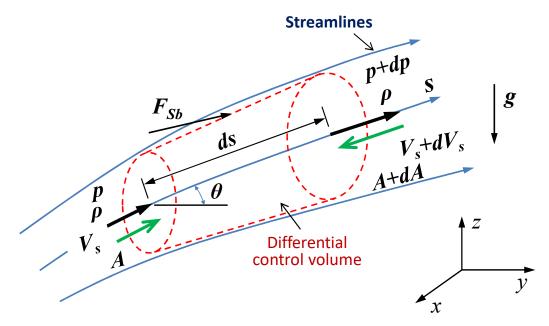
Now, a **differential control volume** is considered. Using this approach, the differential equations can be obtained which will describe a flow field.

The differential control volume is fixed in space and bounded by flow streamlines, is thus an element of a stream tube as shown in Fig. The length of the control volume is ds.

Because the control volume is bounded by streamlines, the flow across the bounding surfaces occurs only at the end sections.

Apply the continuity and momentum equations considering:

- (i) Steady flow
- (ii) Inviscid flow (no friction, ideal fluid flow,  $\mu = 0$ )
- (iii) Incompressible flow (density is constant)
- (iv) Irrotational flow (zero vorticity)
- (v) Flow along a streamline





a. Continuity equation

$$\frac{d}{dt} \int_{CV}^{=0} \rho \, d\mathcal{V} + \int_{CS} \rho \left( \vec{\mathbf{V}} \cdot \hat{\mathbf{n}} \right) dA = 0$$

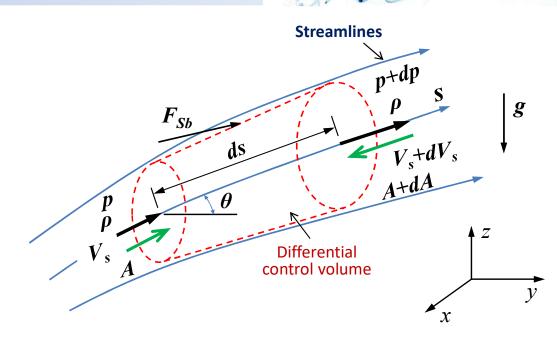
$$\Rightarrow \int_{\rm CS} \rho\left(\vec{\mathbf{V}} \cdot \hat{\mathbf{n}}\right) dA = 0$$

$$\Rightarrow -\rho V_s A + \{\rho (V_s + dV_s) (A + dA)\} = 0 \Rightarrow -\rho V_s A + \rho (V_s + dV_s) (A + dA) = 0 \Rightarrow -\rho V_s A + \rho V_s A + \rho V_s dA + \rho A dV_s + \rho dA dV_s = 0$$

product of two differentials  $dAdV_s$  is insignificant compared to other terms.

 $\Rightarrow V_s dA + A dV_s = 0$ 

**continuity equation** for the differential control volume







b. Momentum equation (along steamwise direction)

$$\sum \left(\vec{F}_{S} + \vec{F}_{B}\right) = \frac{d}{dt} \int_{CV}^{=0} \vec{V}\rho \, dV + \int_{CS} \vec{V}\rho \left(\vec{V} \cdot \hat{\mathbf{n}}\right) dA$$
$$\Rightarrow \sum \left(F_{SS} + F_{BS}\right) = \int_{CS} V_{S}\rho \left(\vec{V} \cdot \hat{\mathbf{n}}\right) dA$$

(along streamwise direction, *s*)

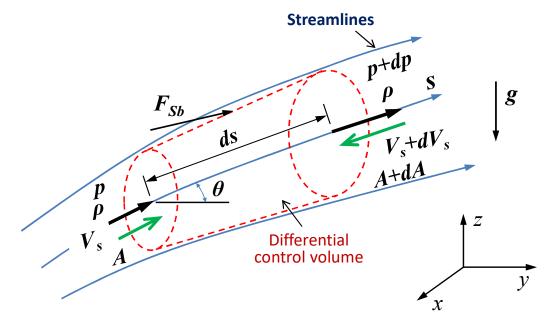
**Surface force** only comes from the pressure ( $\mu = 0$ ):

$$F_{S_s} = pA - (p + dp)(A + dA) + \left(p + \frac{dp}{2}\right)dA$$

(Right face)

(Left face)

(bounding stream surface) (average pressure acting on the bounding surface times the area component of the stream surface in s-direction, dA)



**Fig.** Differential control volume for momentum analysis of flow through a stream tube

$$\Rightarrow F_{S_s} = pA - pA - pdA - Adp - dpdA + pdA + \frac{dp}{2} dA$$

 $\Rightarrow F_{S_{*}} = -Adp$ 

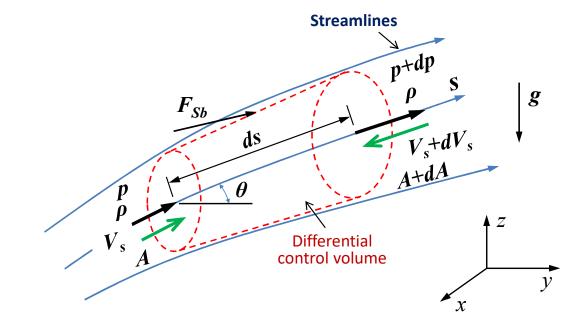
product of two differentials *dpdA* is insignificant compared to other terms.





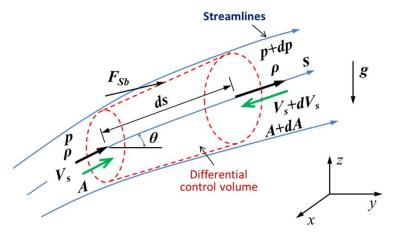
**Body force** acting along *s*-direction:

$$F_{B_s} = \rho \left(-g \sin \theta \right) \left(A + \frac{dA}{2}\right) ds$$
$$\Rightarrow F_{B_s} = -\rho g \left(A + \frac{dA}{2}\right) dz$$
$$\Rightarrow F_{B_s} = -\rho g A dz - \rho g \frac{dA}{2} dz$$
$$\implies F_{B_s} = -\rho g A dz$$









Right hand side of momentum equation:

**Fig.** Differential control volume for momentum analysis of flow through a stream tube

$$\int_{CS} \vec{\mathbf{V}} \rho \left( \vec{\mathbf{V}} \cdot \hat{\mathbf{n}} \right) dA = V_s \left( -\rho V_s A \right) + \left( V_s + dV_s \right) \left\{ \rho \left( V_s + dV_s \right) \left( A + dA \right) \right\}$$

$$\Rightarrow \int_{CS} \vec{\mathbf{V}} \rho \left( \vec{\mathbf{V}} \cdot \hat{\mathbf{n}} \right) dA = -\rho V_s^2 A + \left( V_s + dV_s \right) \left( \rho V_s A + \rho V_s dA + \rho A dV_s + \rho dV_s dA \right)$$

$$\Rightarrow \int_{CS} \vec{\mathbf{V}} \rho \left( \vec{\mathbf{V}} \cdot \hat{\mathbf{n}} \right) dA = -\rho V_s^2 A + \left( V_s + dV_s \right) \left( \rho V_s A \right)$$

$$= 0 \quad V_s dA + A dV_s = 0 \text{ (continuity )}$$

$$\Rightarrow \int_{CS} \vec{\mathbf{V}} \rho \left( \vec{\mathbf{V}} \cdot \hat{\mathbf{n}} \right) dA = -\rho V_s^2 A + \rho V_s^2 A + \rho V_s A dV_s$$

$$\Rightarrow \int_{\rm CS} \vec{\mathbf{V}} \rho \left( \vec{\mathbf{V}} \cdot \hat{\mathbf{n}} \right) dA = \rho V_s A dV_s$$



Now, momentum equation (along steamwise direction)

$$\sum \left( F_{S_s} + F_{B_s} \right) = \int_{CS} V_s \rho \left( \vec{\mathbf{V}} \cdot \hat{\mathbf{n}} \right) dA$$

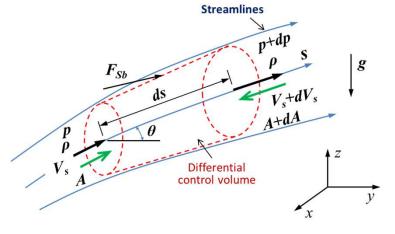
$$\Rightarrow -Adp - \rho gAdz = \rho V_s AdV_s$$

#### Dividing both sides by $\rho A$ :

$$\Rightarrow -\frac{dp}{\rho} - gdz = V_s dV_s = d\left(\frac{V_s^2}{2}\right)$$

$$\Rightarrow \frac{dp}{\rho} + d\left(\frac{V_s^2}{2}\right) + gdz = 0$$

**Euler differential equation** for steady inviscid incompressible fluid flow .



**Fig.** Differential control volume for momentum analysis of flow through a stream tube



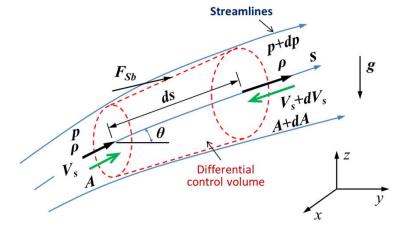




Integrate the Euler equation along a streamline:

$$\int \frac{dp}{\rho} + \int d\left(\frac{V_s^2}{2}\right) + \int gdz = \text{Constant}$$

$$\Rightarrow \frac{p}{\rho} + \frac{{V_s}^2}{2} + gz = \text{Constant}$$



**Fig.** Differential control volume for momentum analysis of flow through a stream tube

Suffix s can be dropped conveniently (since fluid flows along the streamline)

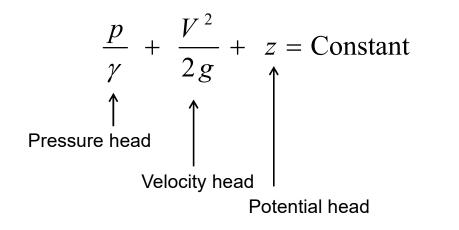
 $\Rightarrow \frac{p}{\gamma} + \frac{V^2}{2g} + z = \text{Constant}$ 

#### Bernoulli equation.

(Most famous and mostly used equation in fluid dynamics)

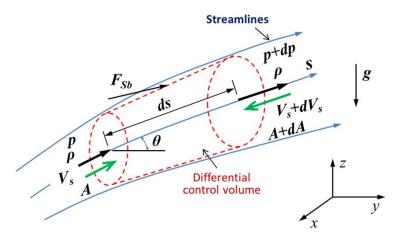


#### **Bernoulli equation**



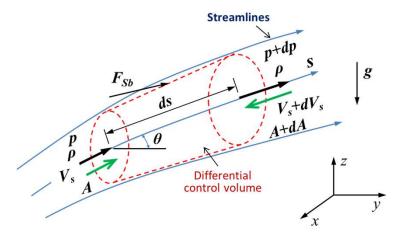
Subjected to the following restrictions in fluid flow:

- (i) Steady flow
- (ii) Inviscid flow (no friction, ideal fluid flow,  $\mu = 0$ )
- (iii) Incompressible flow (density is constant)
- (iv) Irrotational flow
- (v) Flow along a streamline









**Fig.** Differential control volume for momentum analysis of flow through a stream tube

Considering any two points along a streamline, **Bernoulli Equation** yields:

$$\frac{p_1}{\gamma} + \frac{V_1^2}{2g} + z_1 = \frac{p_2}{\gamma} + \frac{V_2^2}{2g} + z_2$$

